



The NASA Blue Marble

Spatio-Temporally Consistent Satellite Composites

Options for Enhancing the Realism of Google Maps?

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Blue Marble Research, NASA/GSFC, CSU and ETH

The Original Blue Marble

Photograph taken on board Apollo 17

- 7 December 1972
- 45'000km away from earth
- 70mm Hasselblad, 80mm lens

Credits

Eugene Cernan,
Ronald Evans and
Jack Schmitt



Blue Marble 2000

False color satellite data visualization

- September 1997
- Satellite Sensors:
 - NOAA GOES-10
 - NOAA AVHRR
 - SeaWiFS
- 5km spatial resolution

Credits

Reto Stöckli, Alan
Nelson and Fritz Hasler



Blue Marble 2002

True color satellite data visualization

- June-August 2001
- MODIS (TERRA)
- 1km spatial resolution
 - land
 - ocean
 - sea-ice
 - clouds
 - lights



Credits

Reto Stöckli, Rob Simmon and MODIS science team

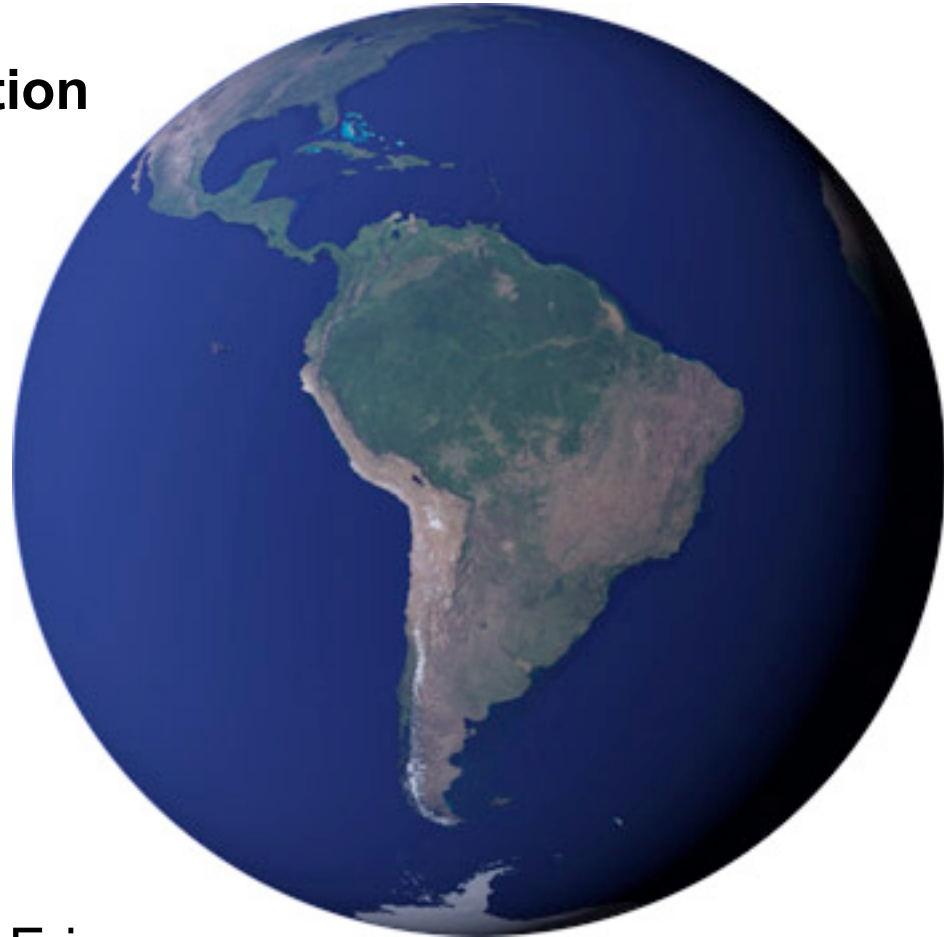
Blue Marble Next Generation

Numerical satellite data processing and visualization

- 500 m global, land
- seasonal dynamics
- spatial consistency with temporal statistics
- widely applied in media, exhibitions, education ...
- freely available

Credits:

Reto Stöckli, Rob Simmon, Eric Vermote, MODIS Science Team

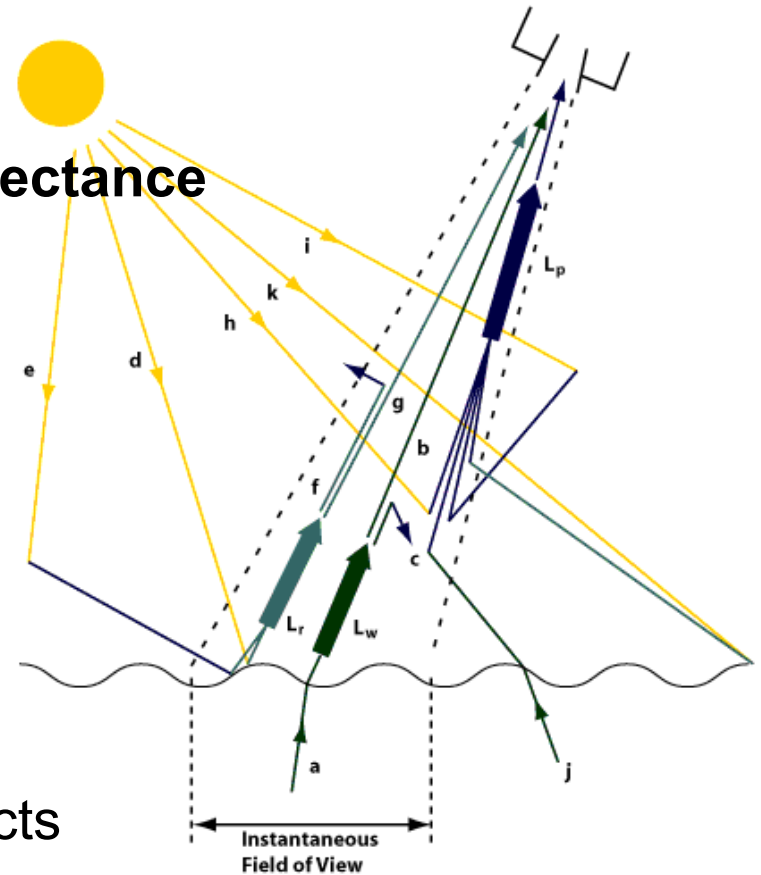


Scene Processing

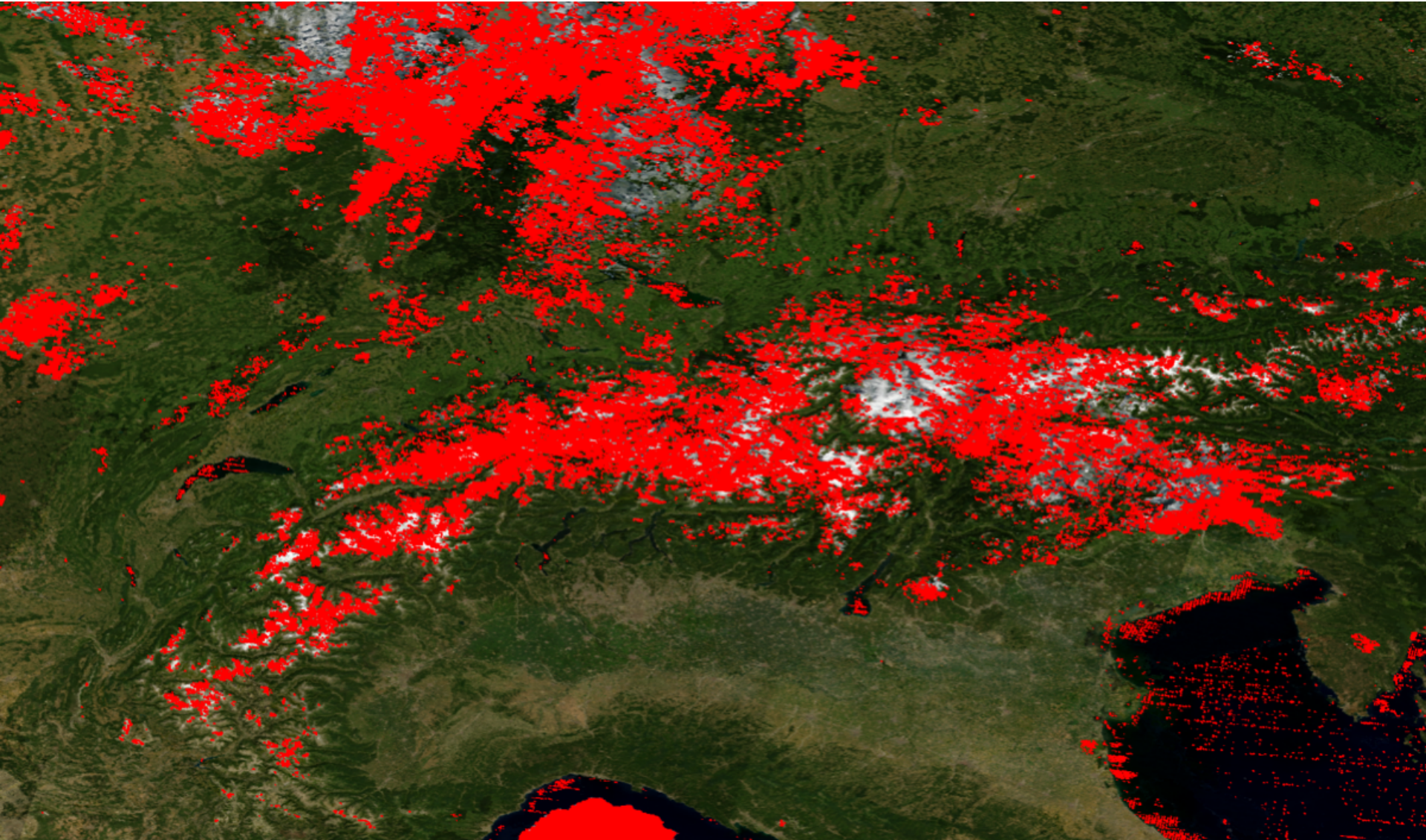
Achieve cloud-free surface reflectance

Mandatory for each scene:

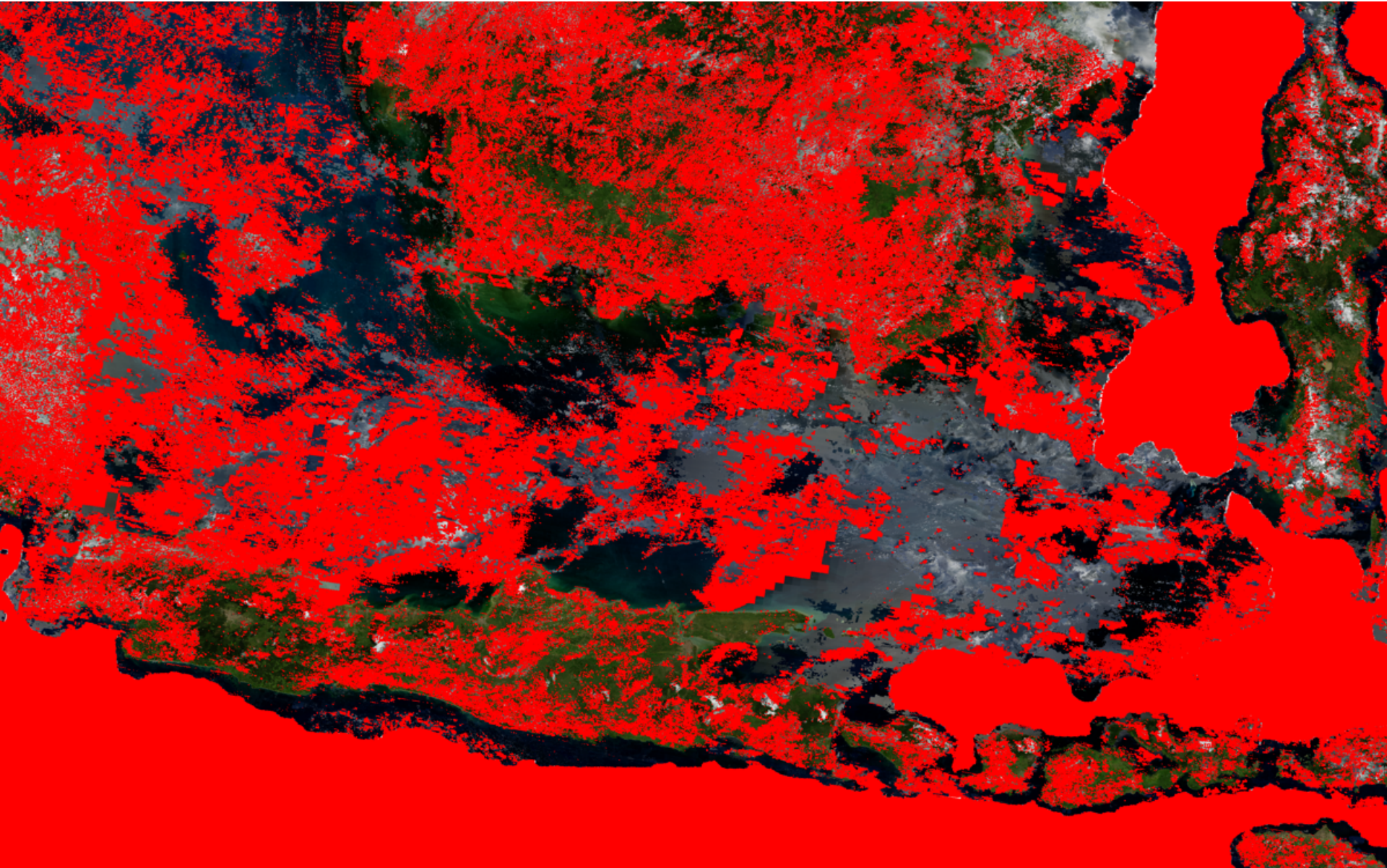
- registration & navigation
 - removal of artifacts
 - orthorectification
 - radiance (inter-) calibration
 - cloud masking
 - spectral conversion
 - correction of atmospheric effects
-
- **applicable to Google Maps (incl. Landsat and Ikonos)**
 - **computationally expensive, mature algorithms available**
 - **requires Image metadata and physical retrieval models**



Screening & Correction of Atmospheric Effects and Cloudiness



Tropics ... where is the clear sky?



Scene Compositing

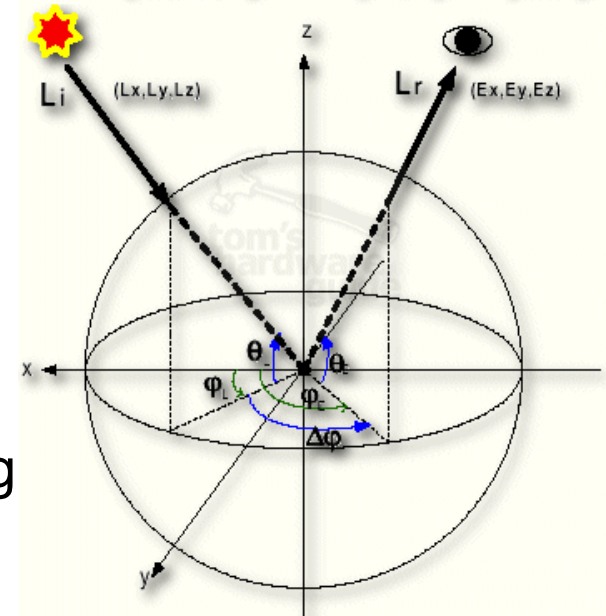
Achieve spatial consistency

- remove surface BRDF effects
- seasonal dynamics of vegetation
- remove gaps by temporal compositing

Possible solutions (model inversion)

- fit 2nd and 3rd order fourier series
- bayesian data assimilation
- multi-sensor parameter estimation
- **maybe applicable to Google Maps**
- **requires “high” temporal coverage (Landsat? EO-1?)**
- **development of new algorithms, scientific innovation!**

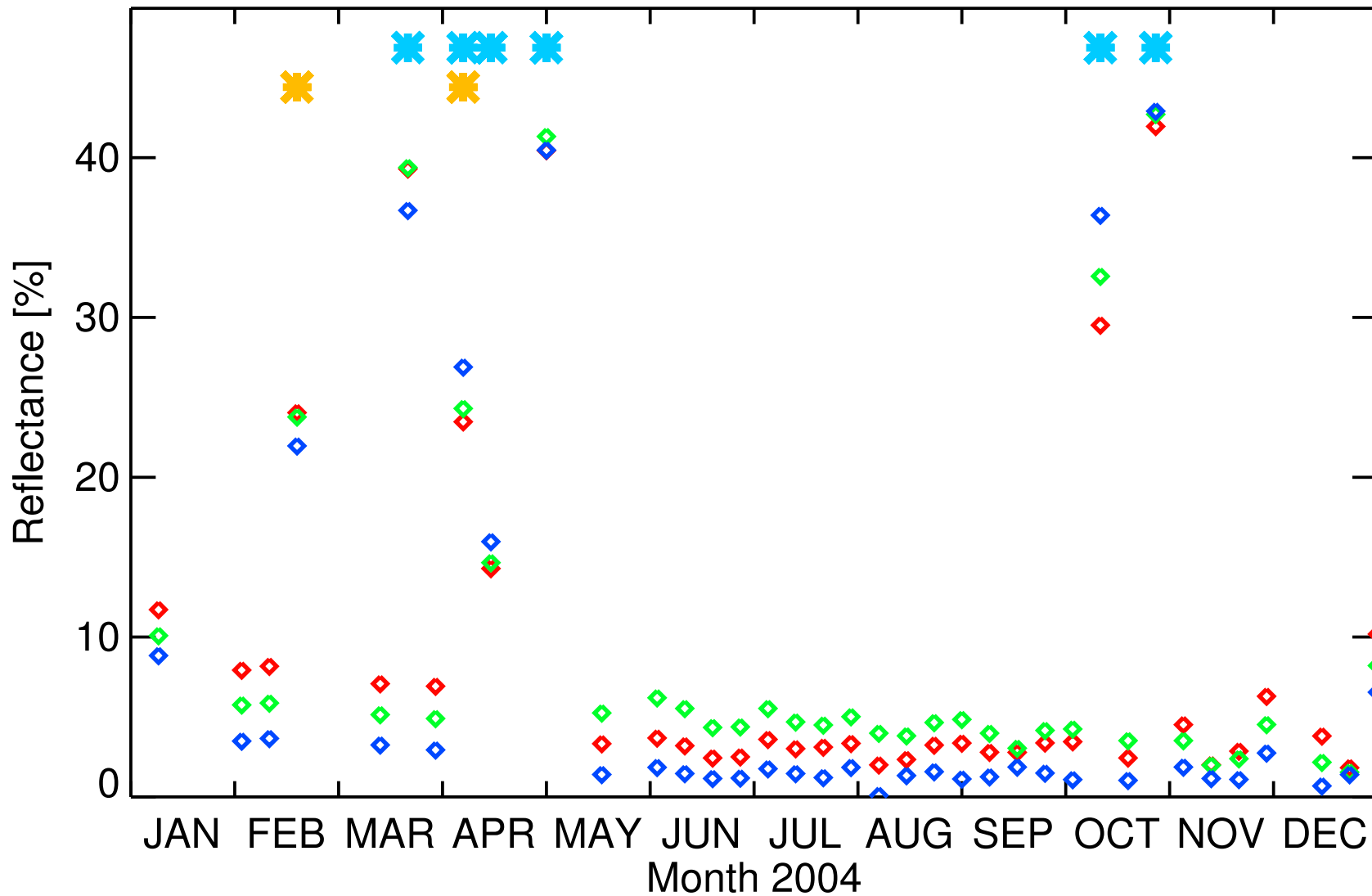
$$\text{BRDF}(\omega_i, \omega_r, \lambda) = dL_r(\omega_r, \lambda) / L_i(\omega_i, \lambda)$$



ORIG

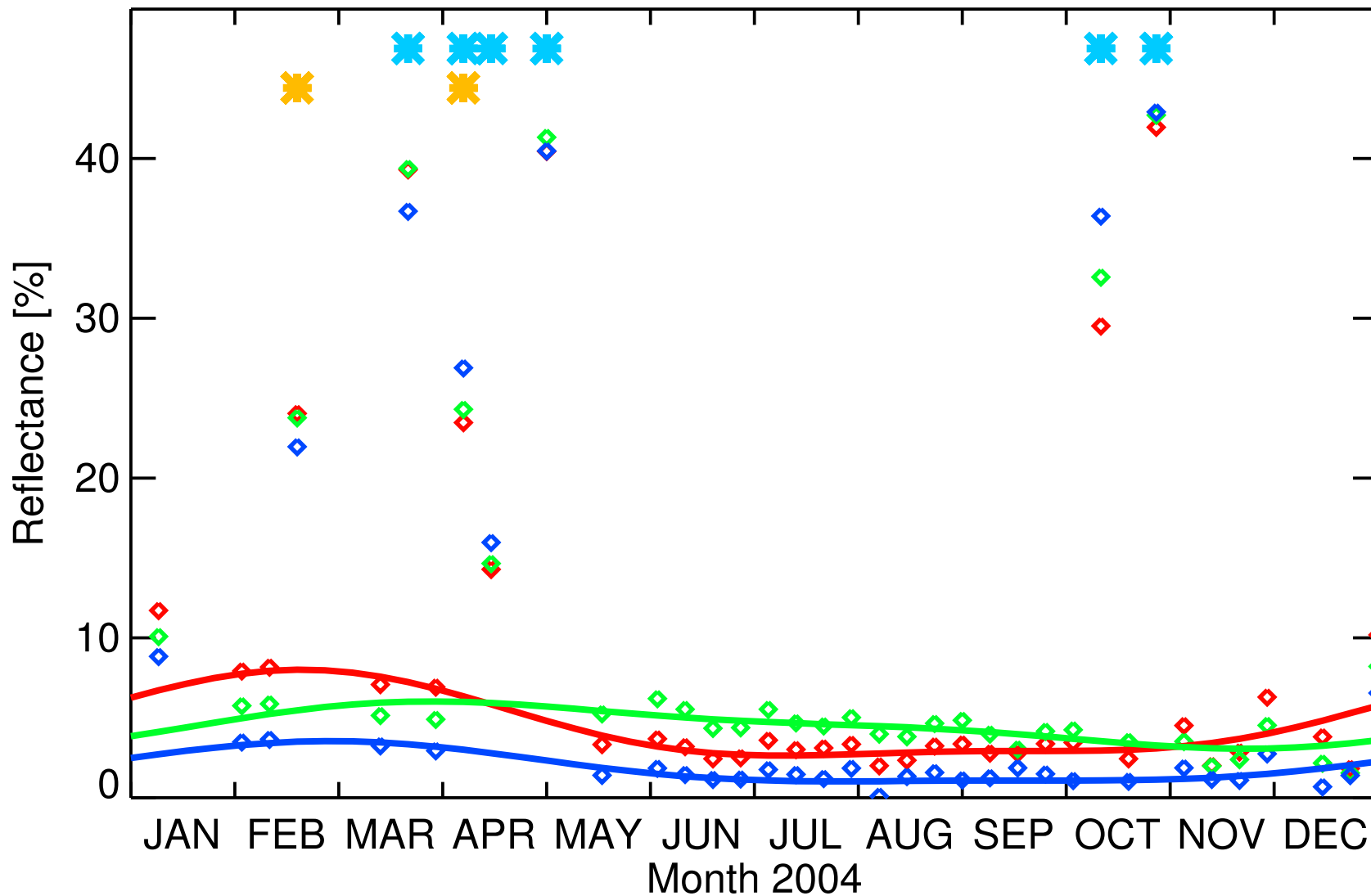


Mixed forests

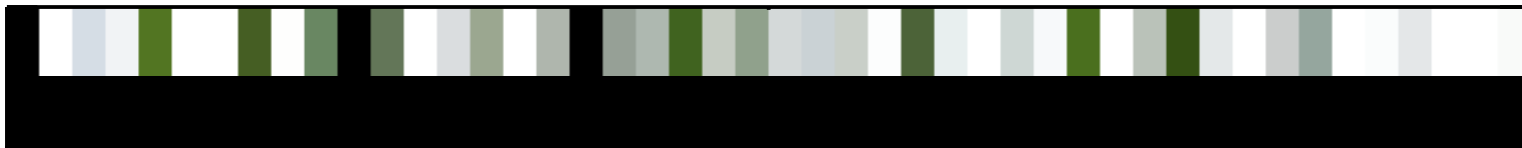




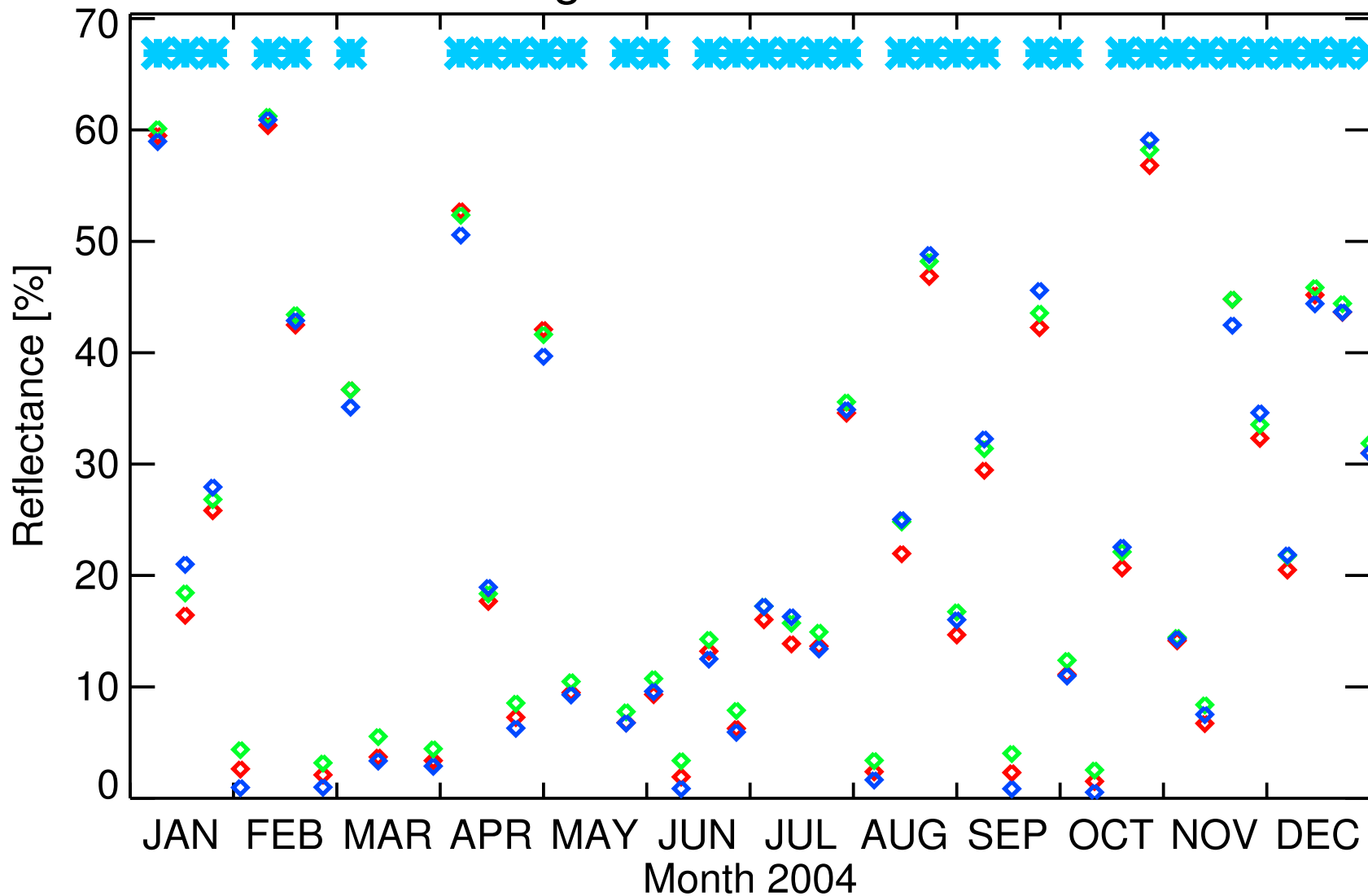
Mixed forests



ORIG

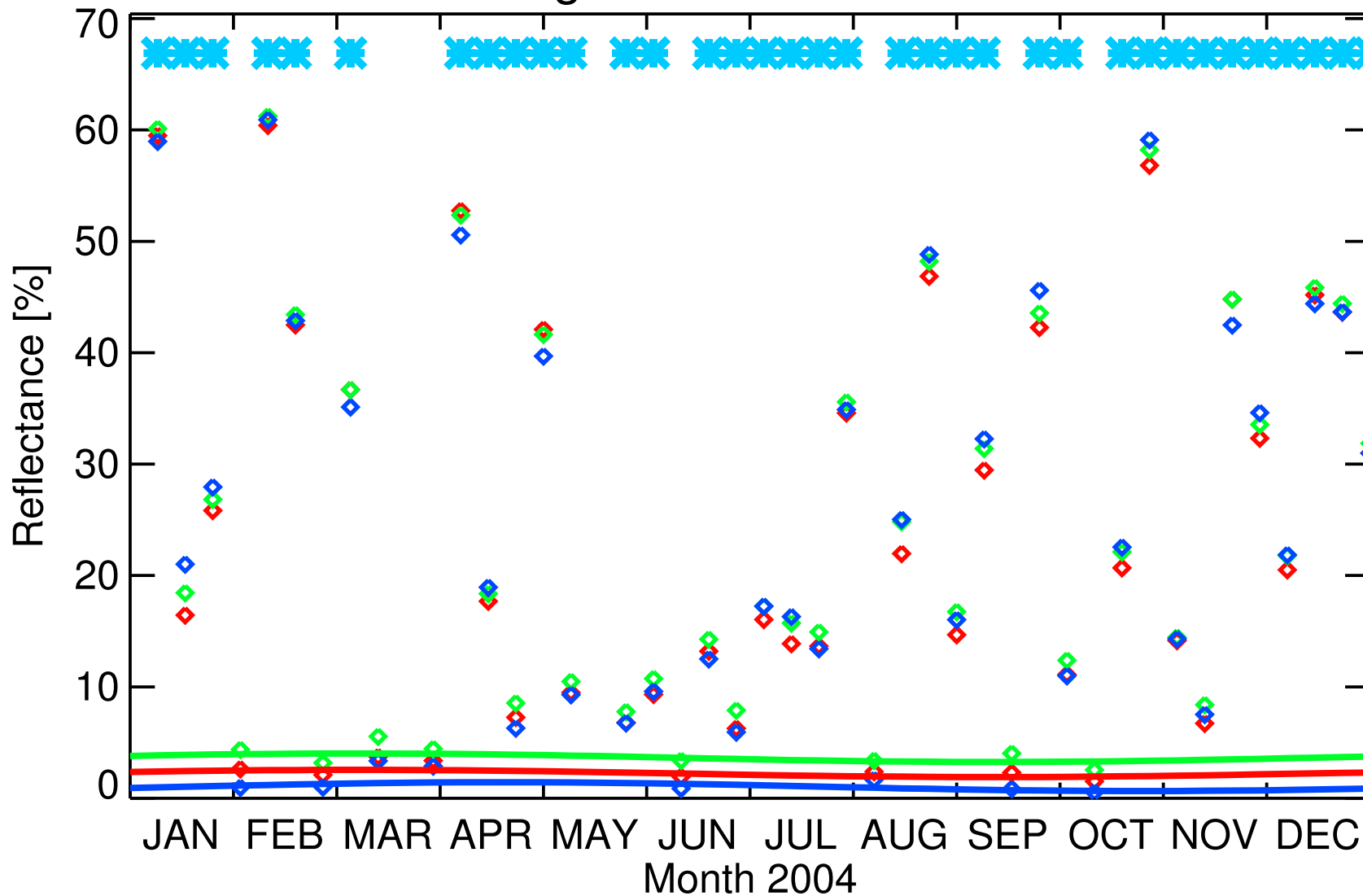


Evergreen broadleaf forest





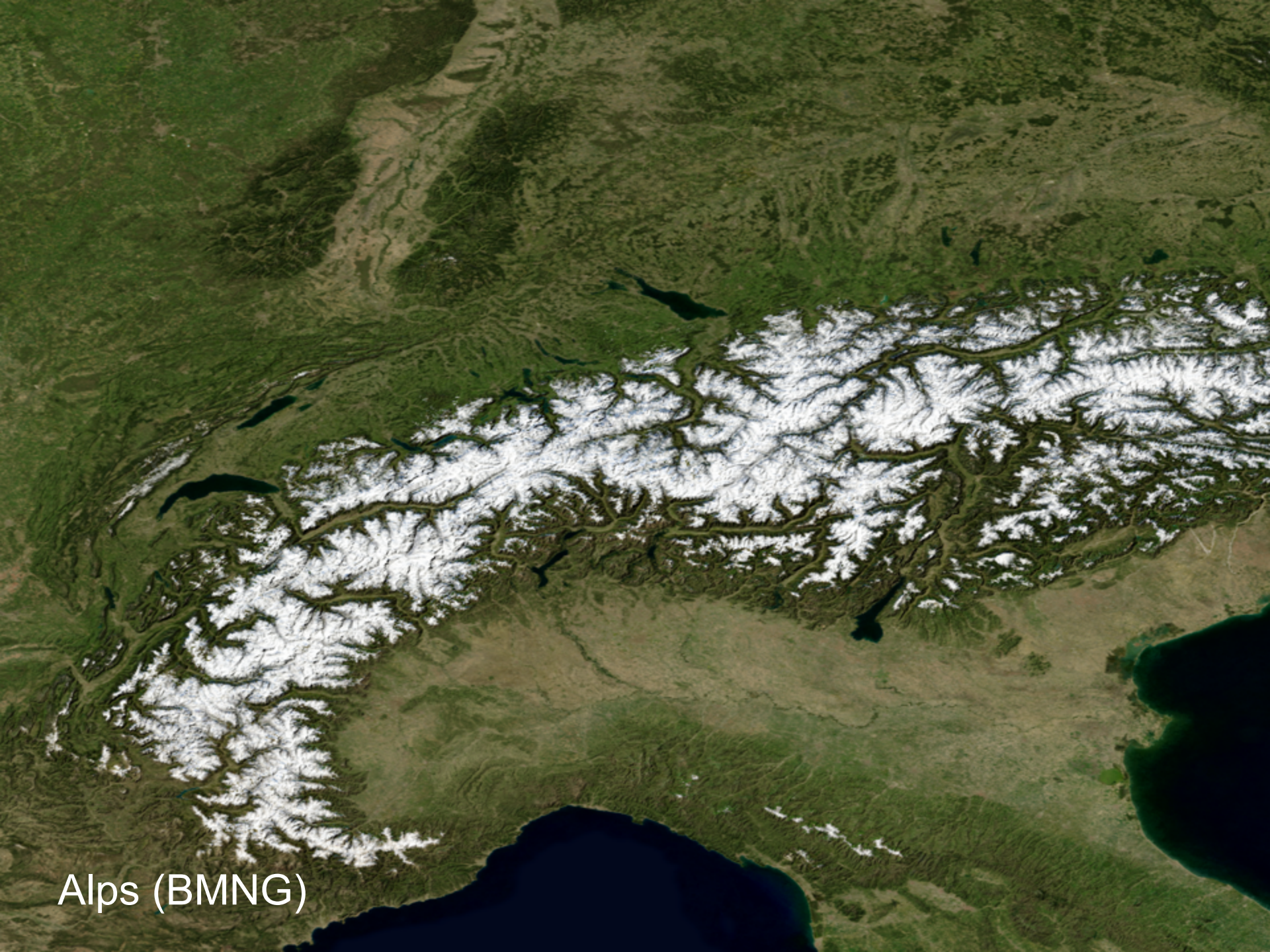
Evergreen broadleaf forest





Mt Kenya

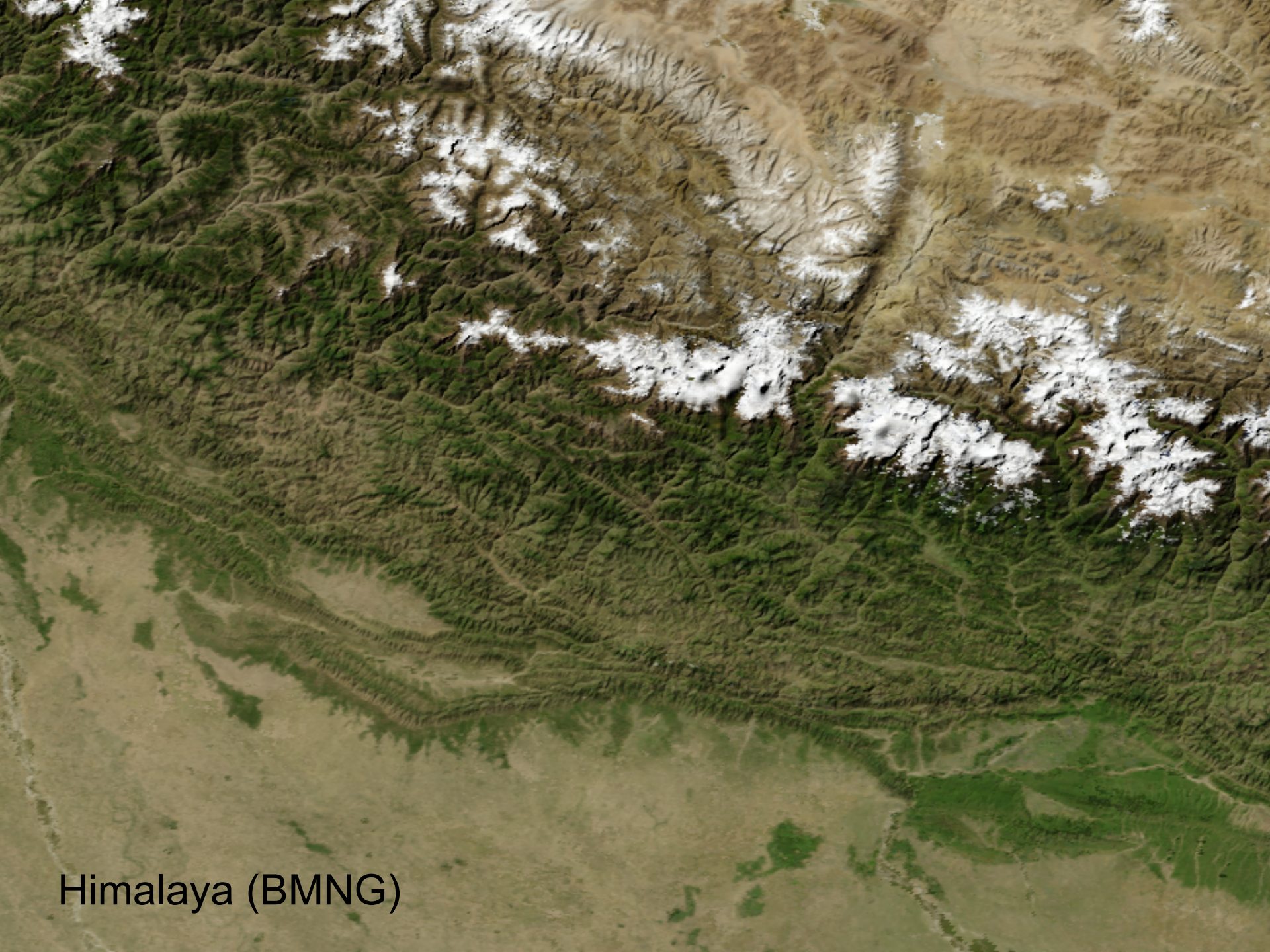
Nairobi



Alps (BMNG)



Alps (Google)



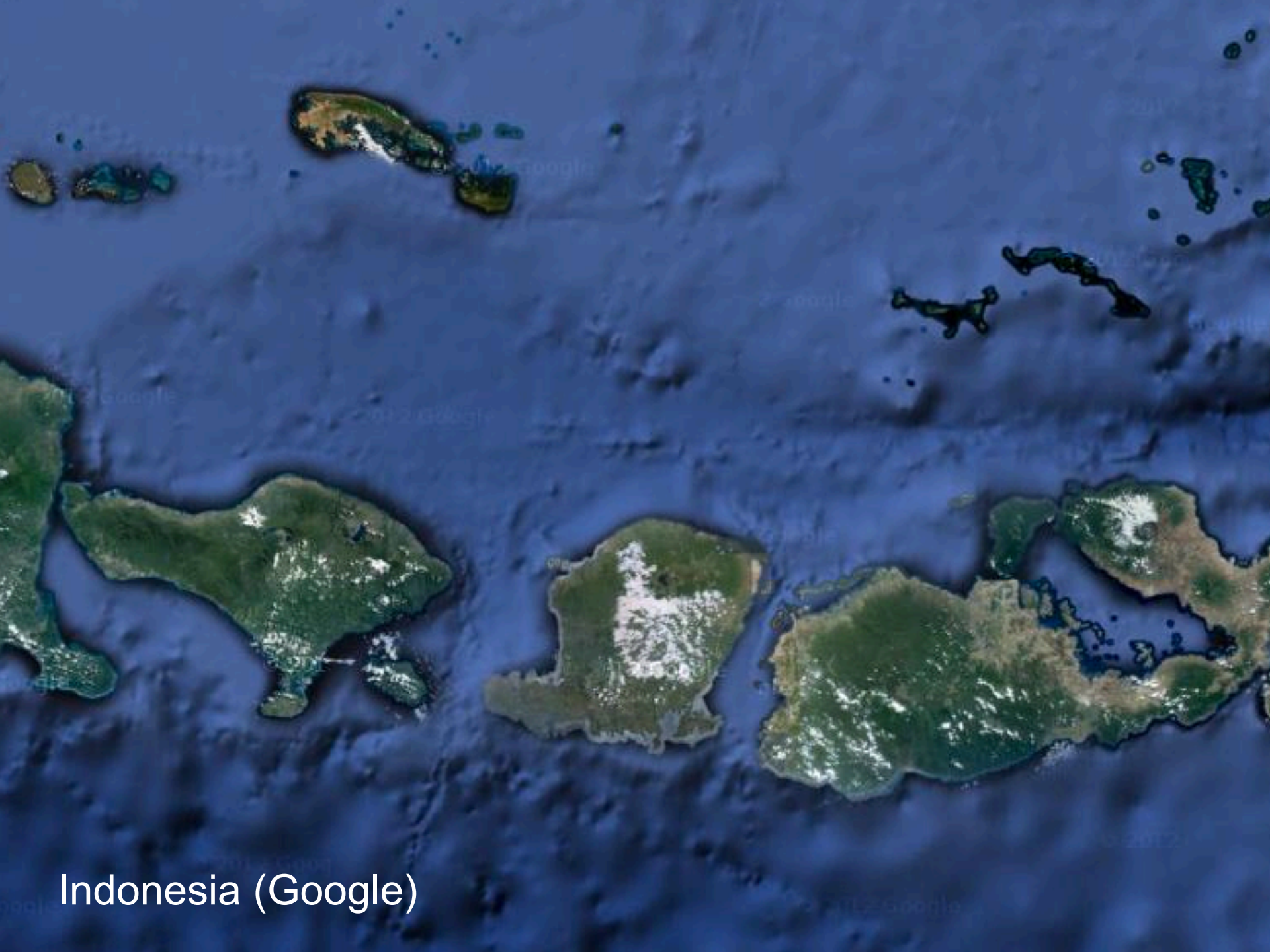
Himalaya (BMNG)



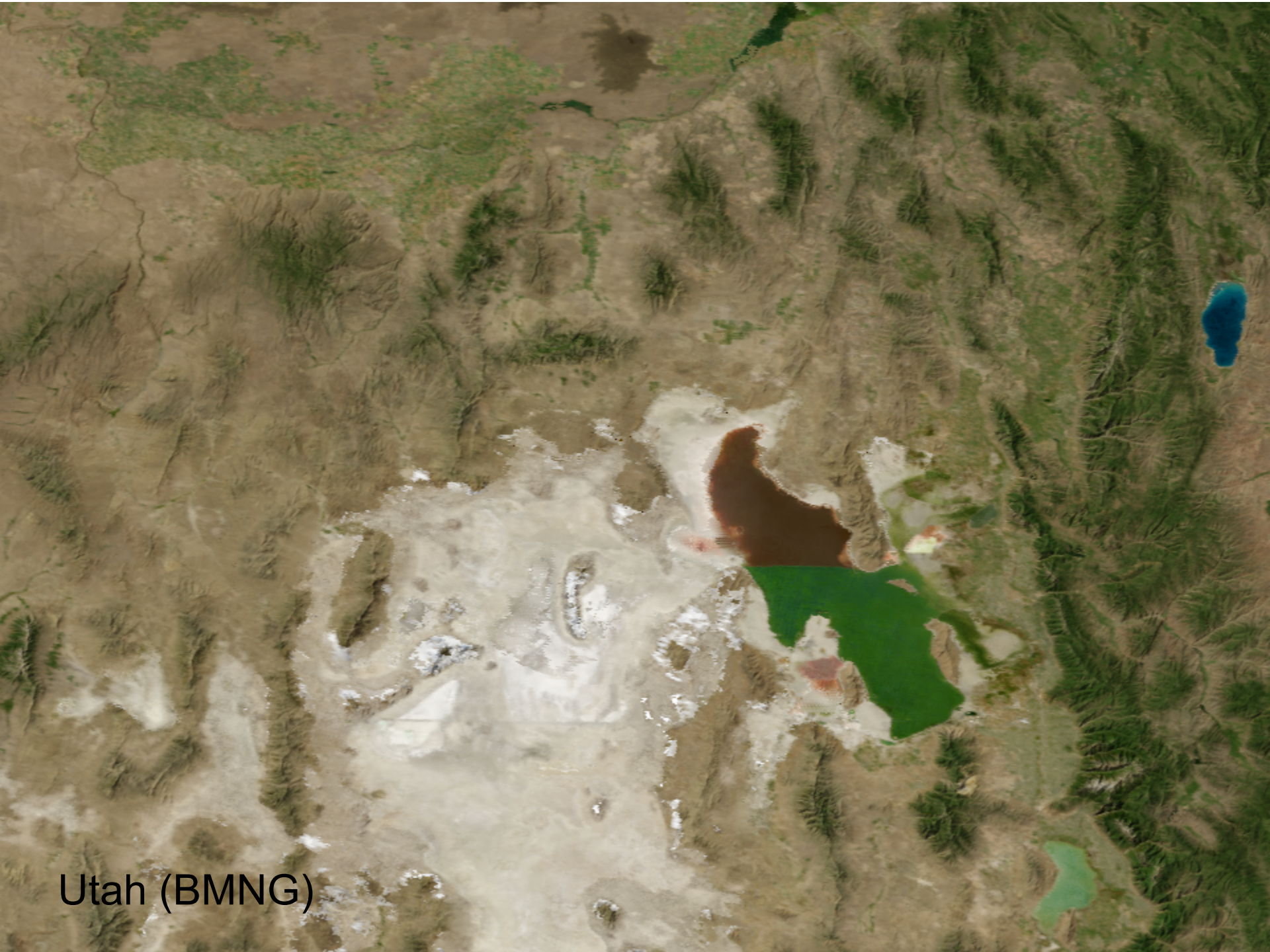
Himalaya (Google)



Indonesia (BMNG)



Indonesia (Google)



Utah (BMNG)



Utah (Google)